

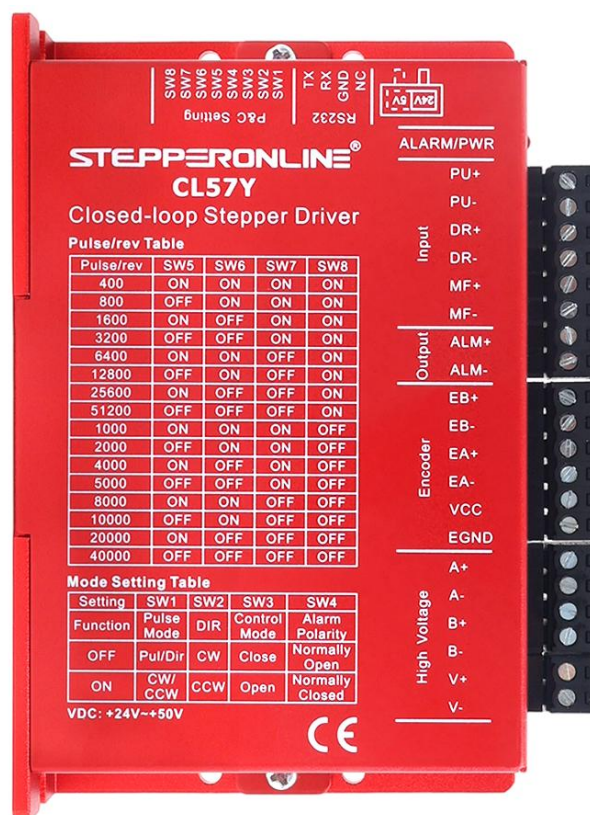
STEPPERONLINE®

User Manual

CL57Y(V20)

Pulse type close loop stepper driver instruction manual

Version: V1.0



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Revision history

Version	Description	Date	Remark
V1.0	First edition release	2025.05.20	

Introduction

Thank you for using this stepper drive.

Before using this product, be sure to read this manual carefully to understand the necessary safety information, precautions, and operation methods.

The wrong operation can lead to extremely serious consequences.

Statement

The design and manufacture of this product does not have the ability to protect personal safety from the threat of mechanical systems. Users are requested to consider safety protection measures during the design and manufacture of mechanical systems to prevent accidents caused by improper operation or abnormal products.

Due to product improvements, the contents of the manual are subject to change without notice.

Our company will not be responsible for any modification of the product by the user.

When reading, please note the following marks in the manual:



Remind you to pay attention to the main points in the text.



Indicates that improper operations may result in personal injury or equipment damage.

Chapter 1 Overview

1.1 Product Introduction

CL57Y(V20) adopts a new generation of 32-bit DSP control technology and power Angle control technology, the maximum speed can reach 3000rpm,And the high-speed torque attenuation is far lower than that of the ordinary open-loop driver, which can greatly improve the high-speed performance and torque of the stepper motor,It can effectively reduce the heating and vibration of the motor, thus improving the processing efficiency and accuracy of the machine.The driver adopts load-based current control technology, which can effectively reduce motor heat and prolong motor service life.The built-in position and alarm output signals of the driver are convenient for the upper computer to monitor and control. Position out of tolerance alarm function guarantee

- The current size is intelligently adjusted according to the load condition
- Can drive 23/24 series stepper motor.
- The optocoupler isolates the differential signal input
- The impulse response frequency is up to 200KHz.
- Voltage input range: DC24-50V;
- With over current, over voltage, under voltage, position over error protection

1.2 Application Field

This product is suitable for a variety of large automation equipment and instrument applications. For example: engraving machine, special industrial sewing machine, stripping machine, marking machine, cutting machine, laser phototypesetting, plotter, CNC machine tools and other automation equipment and instruments.

Chapter 2 Performance Indicators

2.1 Electrical Characteristic

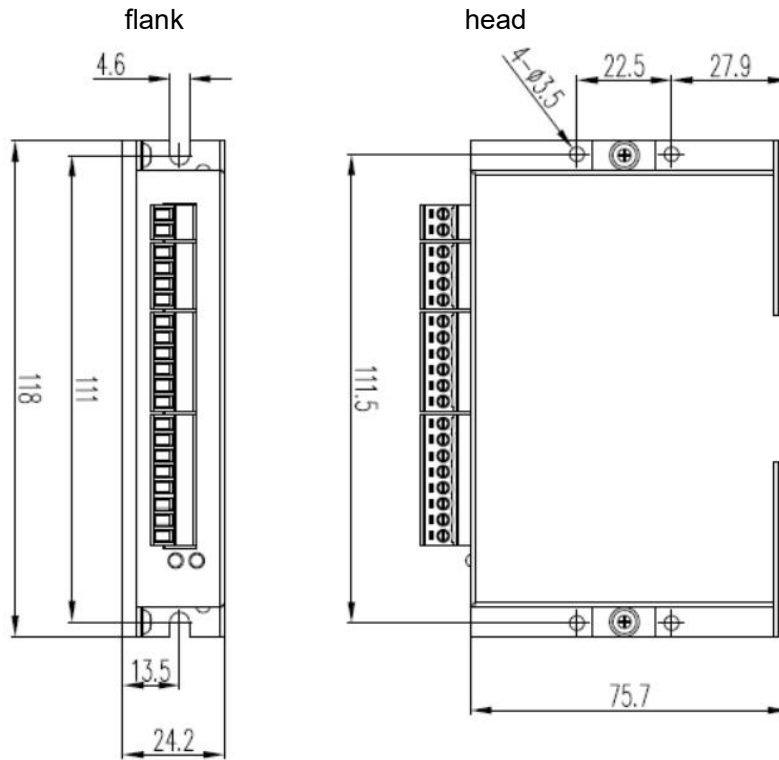
Argument	CL57Y(V20)			
	Minimum value	Typical value	Maximum value	Unit
Continuous output current	-	2.3	5.6	A
Input supply voltage	24.0	-	50.0	Vdc
Logic input current	1.0	-	7.5	mA
Pulse frequency	-	-	200	kHz
Insulation resistance	10	-	-	MΩ

2.2 Using Environment

Cooling mode	Natural cooling	
Use environment	Use occasion	Try to stay away from other heating equipment, avoid dust, oil mist, corrosive gas, strong vibration places, flammable gas and conductive dust are prohibited
	Temperature	0°C~50°C
	Humidness	40—90%RH (non-condensation)
	Vibration	10~55Hz/0.15mm
Storage temperature	-20°C~+70°C	

Chapter 3 Installation

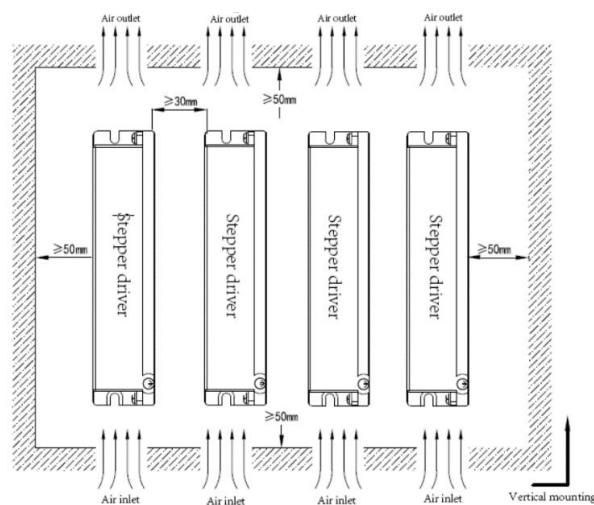
3.1 Mounting Dimension



Mounting dimension (unit: mm)

3.2 Installation Methods

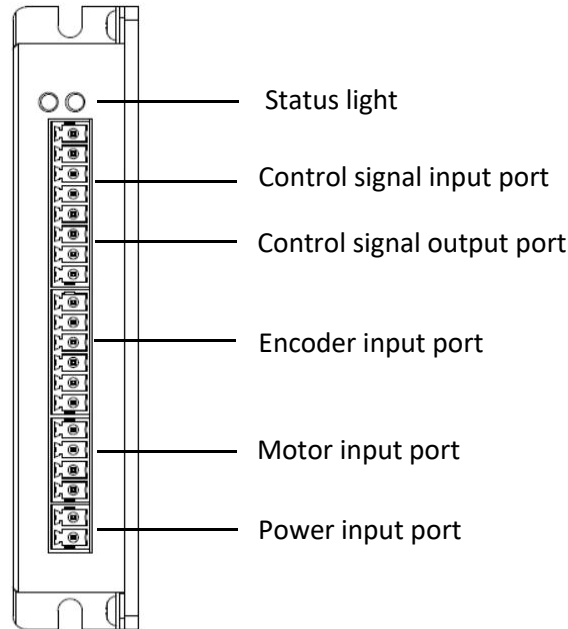
When installing the driver, please use the upright side installation to form strong air convection on the driver surface; If necessary, install a fan close to the driver to force the heat to dissipate to ensure that the driver works within the reliable operating temperature range (the reliable operating temperature of the driver is usually within 50°C, and the operating temperature of the motor is within 80°C).



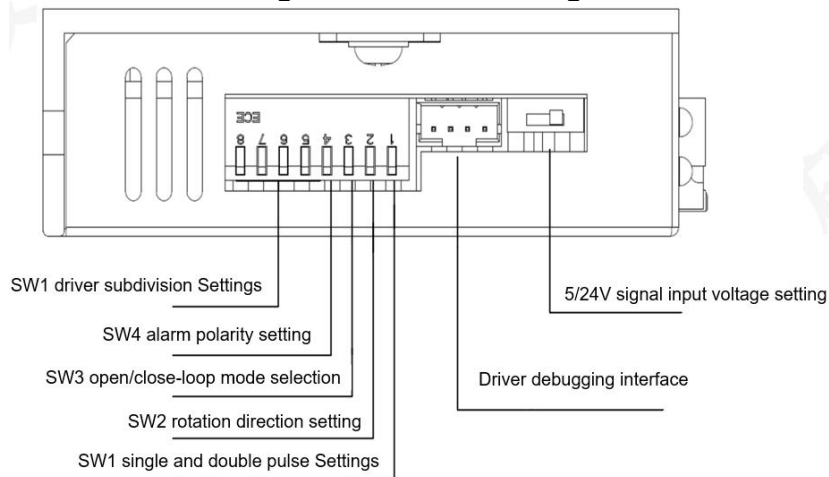
Chapter 4 Driver Ports and Wiring

4.1 Wiring Diagram

- Use the CL57Y(V20) drive according to the interface diagram:



Schematic diagram of the side wiring of the driver



Schematic diagram of the top wiring of the drive



Attention!

- The personnel involved in wiring must have professional ability.
- No live wiring.
- The wiring can only be carried out after the installation is firm.
- Do not connect the power supply wrong, the input voltage should not exceed 50VDC.

4.2 Port Definition

4.2.1 Status Indicator Light

Color	Name	Features
Green	Power indicator light	When the power is on, the green indicator lights up.
Red	Fault indicator light	Drive overcurrent: flash once Drive overvoltage: flicker twice Drive undervoltage: flicker three times Motor is out of phase: flicker four times Drive overtolerance: flicker five times Encoder is incorrect: flicker six times

4.2.2 Drive Dip Settings

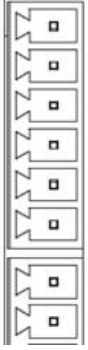
SW1-SW2 is the basic function setting of the driver. Single and double pulse and rotation direction can be set respectively, as shown in the following table

Serial number	Dip code	Function	Dip status	Set content
1	SW1	Single and double pulse Settings	ON	CW&CCW
			OFF	PU&DR
2	SW2	Motor rotation direction setting	ON	CCW
			OFF	CW
3	SW3	drive mode setting	ON	open mode
			OFF	close mode
4	SW4	Alarm polarity setting	ON	ALM singal normal close
			OFF	ALM singal normal open

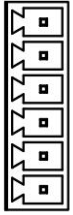

SW5-SW8 can set the drive subdivision, four dip switches a total of 16 gear, respectively set 400-51200 a total of 16 file subdivision, as shown in the following table:

Dip	Default (400)	800	1600	3200	6400	12800	25600	51200	1000	2000	4000	5000	8000	10000	20000	40000
SW5	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF
SW6	ON	ON	OFF	OFF	ON	ON	OFF	OFF	ON	ON	OFF	OFF	ON	ON	OFF	OFF
SW7	ON	ON	ON	ON	OFF	OFF	OFF	OFF	ON	ON	ON	ON	OFF	OFF	OFF	OFF
SW8	ON	ON	ON	ON	ON	ON	ON	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF


4.2.3 Power input and motor port

Port	Lead	Symbol	Feature	Annotation
	1	PU+	Pulse signal input positive end	Digital input and output signals, +5V-+24V can be driven (higher than 5V need to be connected to the current limiting resistance), support a common negative and positive connection
	2	PU-	Pulse signal input negative end	
	3	DR+	Direction signal input positive end	
	4	DR-	Direction signal input negative end	
	5	MF+	Enable the positive end of the signal input	Effectively (low level) turn off the motor coil current, the motor is in the free state and the alarm signal is cleared
	6	MF-	Enable the negative end of the signal input	
	7	ALM+	Alarm signal output positive end	Over current, over voltage, under voltage or out of the alarm, the alarm signal is valid
	8	ALM-	Alarm signal output negative end	

4.2.4 Power input and motor port

Port	Lead	Symbol	Name	Function
	1	A+	Motor interface	Two phase stepper motor connector
	2	A-		
	3	B+		
	4	B-		
	1	V+	Power interface	VDC24-50V
	2	V-		

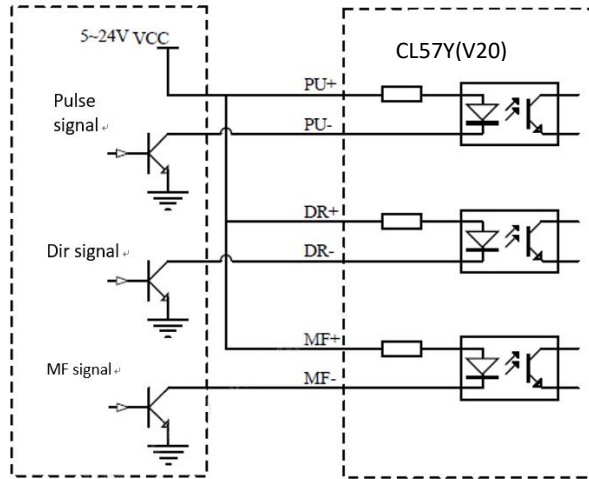
4.2.5 Encoder input port

Port	Lead	Symbol	Name	Function
	1	EB+	Encoder B phase input positive/negative end	Encoder B channel positive input/negative input
	2	EB-		
	3	EA+	Encoder phase A input positive/negative end	Encoder A channel positive input/negative input
	4	EA-		
	5	VCC	Encoder power supply	Encoder 5V power supply
	6	EGND	encoelectrically	encoelectrically

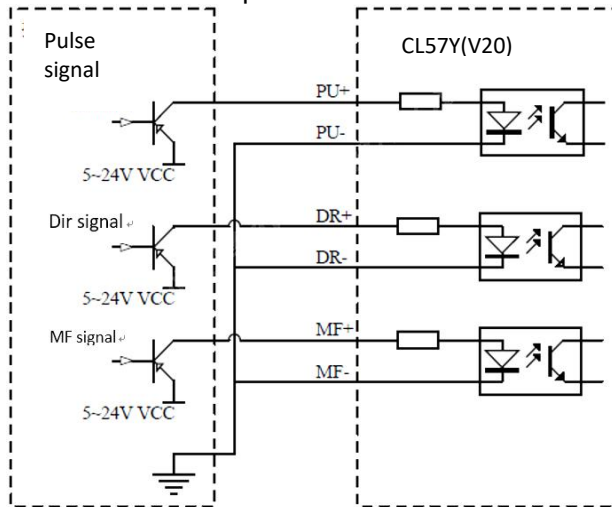
4.3 Input/output port operation

The CL57Y(V20) driver has three digital inputs, photoelectric isolation, and the signal supports 5V-24V input. When the input signal is higher than 24V, the series current limiting resistance is required at the signal input end. The specific wiring diagram is as follows:

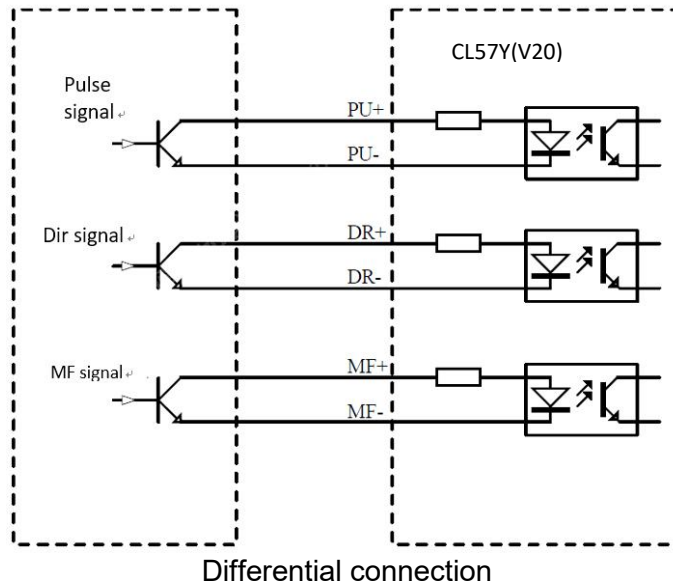
4.3.1 Input Signal



Common positive connection

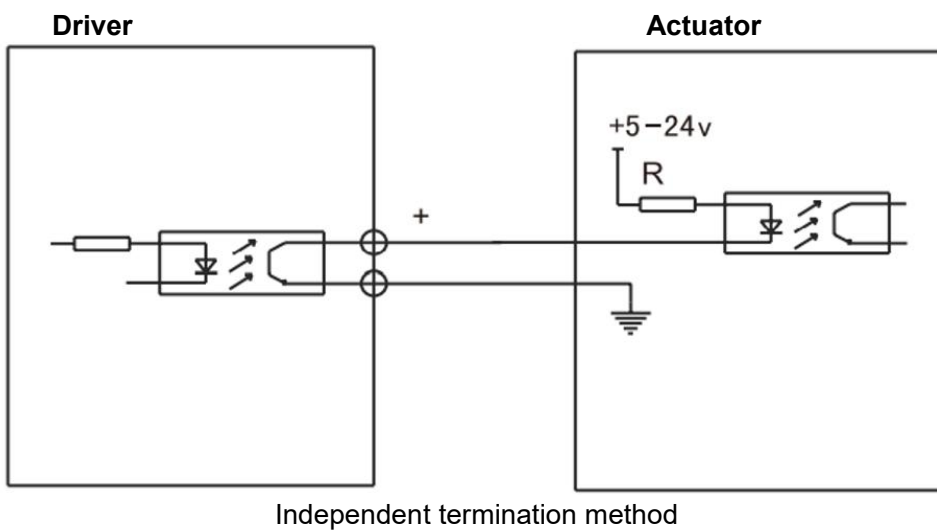
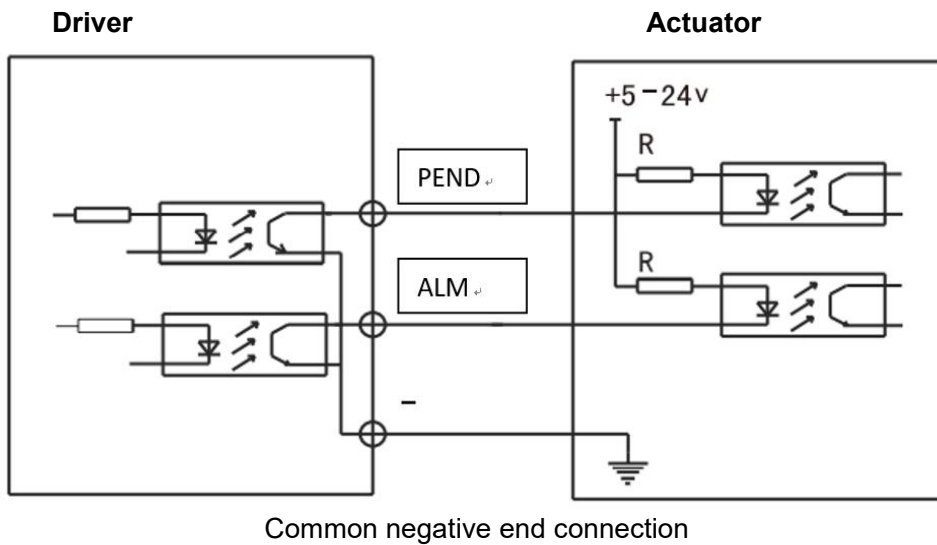


Common negative connection



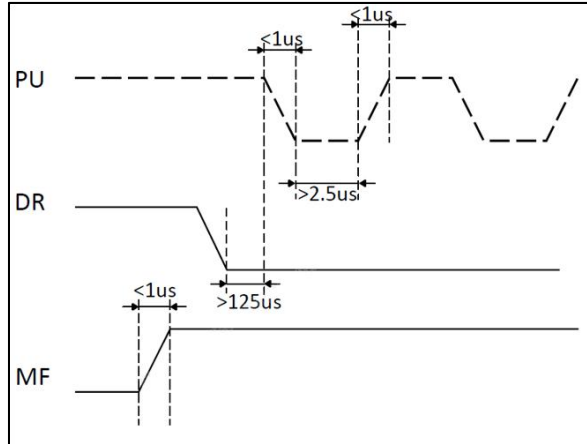
4.3.2 Output Signal

The driver output signal is isolated by an optocoupler and the drive current is max 50mA.



4.4 Signal input timing diagram

CL57Y(V20) driver In order to avoid abnormal operation of the driver control motor, please refer to the following diagram for the timing diagram of the input signal:



Chapter 5 Driver Status Indicators

The CL57Y(V20) driver has an alarm prompt. After the driver alarms, the alarm indicator state indicates the alarm information of the driver. The specific alarm information is shown in the following table.

Fault information	ALM Pilot lamp	Resetting
Overcurrent or interphase short circuit	Flicker once	Power-off reset
Overvoltage of supply	Flicker twice	Automatic restoration of standard voltage
The power supply voltage is too low	Flicker Three times	Automatic restoration of standard voltage
When the motor is out of phase	Flicker four times	The motor is restored after being connected normally
Drive overtolerance	Flicker five times	Release/power-off reset or MF clear out alarm
When the encoder is incorrect	Flicker six times	Restore after the encoder is normal

Chapter 6 General Troubleshooting methods

phenomenon	Possible situation	Solution measure
Motor failure	The power light is off	Check the power supply circuit. The power supply is normal
	The motor locks the shaft but does not turn	The IO signal is weak and the signal current is increased
	Too little speed	Selection speed
	Whether the release signal MF is connected	Will release the signal MF does not connect
	Instruction input error	Check whether the upper computer has a switch output
Motor steering error	Motor reversal	Replace motor wiring sequence or adjust instruction direction
	The motor line has a break	Check whether the cable is in poor contact
	The motor has only one direction	Input port damage
Alarm indicator light	The motor wire is connected incorrectly	Check the wiring
	The voltage is too high or low	Check power supply
	The motor or drive is damaged	Replace the motor or drive
Wrong position or speed	Signal interference	Eliminate interference, reliable grounding
	Instruction input error	Check the upper computer instructions to ensure correct output
	Speed setting error	Check the DIP switch status and connect it correctly
	Motor tripping	Check whether the command speed is too large and the motor selection is small
The driver terminal is burned out	Short-circuit between terminals	Check the power polarity or external short circuit
	The internal resistance between terminals is too large	Check whether excess solder is added to the wire and wire connection to form tin pellets
Motor stalling	The acceleration and deceleration time is too short	Reduce the command acceleration or increase the driver filter parameter
	Motor torque too small	Select high torque motor
	Heavy load	Check the load weight and quality, adjust the mechanical structure
	Too little current	Check dip switches to increase the output current of the driver