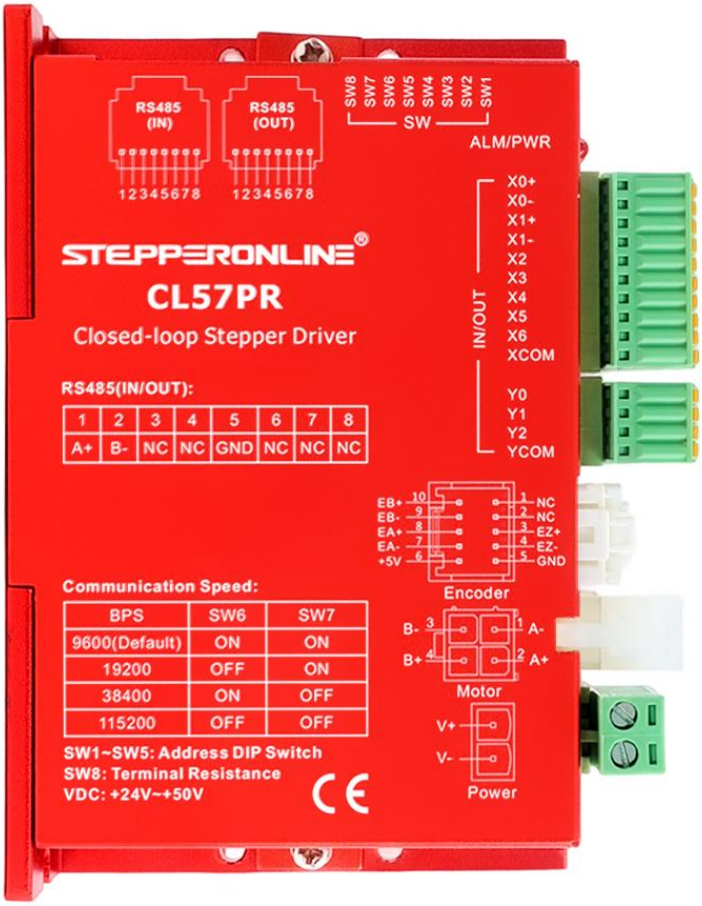
User Manual

CL57PR

Bus stepper driver instruction manual

Version：V1.0



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Revision history

Versio	Description	Date	Remark
V1.0	First edition release	2025.04.15	

Introduction

Thank you for using this stepper drive.

Before using this product, be sure to read this manual carefully to understand the necessary safety information, precautions, and operation methods.

The wrong operation can lead to extremely serious consequences.

Statement

The design and manufacture of this product does not have the ability to protect personal safety from the threat of mechanical systems. Users are requested to consider safety protection measures during the design and manufacture of mechanical systems to prevent accidents caused by improper operation or abnormal products.

Due to product improvements, the contents of the manual are subject to change without notice.

Our company will not be responsible for any modification of the product by the user.

When reading, please note the following marks in the manual:

Remind you to pay attention to the main points in the text.

Indicates that improper operations may result in personal injury or equipment damage.

Chapter 1 Overview

1. 1 Product introduction

CL57PR bus stepper motor driver is based on the digital closed-loop stepper drive with bus communication and single-axis controller functions. Bus communication using RS485 bus communication interface, support standard MODBUS-RTU protocol, users can control up to 30 drivers at the same time, at the same time, the driver has a rich input and output interface, used to complete position control, speed control, return to the origin and other single-axis motion control functions.

1.2 Peculiarity

- New generation 32-bit DSP technology, high cost performance, good stability, low noise, low vibration.
- Bus communication using RS485 bus communication interface, support standard MODBUS-RTU protocol, users can simultaneously control up to 31 drivers.
- Has a wealth of input and output interfaces, used to complete position control, speed control, return to the origin and other single-axis motion control functions.
- The user can set the current, subdivision and lock the current size through the bus; Control motor start and stop and query the real-time state of motor operation.
- Supports four motion control function modes: CSP, PP, PV and HOME.
- 2 photoelectric isolation high-speed differential input interface, can control the start and stop of the motor through external signals
- 5 photoelectric isolation single-end input interfaces to receive external control signals to enable the driver to start, stop, and emergency stop
- Three photoelectric isolation output ports to output driver status and control signals.
- Subdivision 400-51200 arbitrary adjustable, smooth and accurate current control, motor heating is small.
- The drive current RMS is adjustable below 5.0A.
- Voltage range: DC24-50V.
- has over voltage, under voltage, over current and other protection functions.

1.3 Application field

This product is suitable for various medium and large scale automation equipment and instrument applications. For example: 3C non-standard industry, battery industry, photovoltaic industry TOP customer applications, mainly used for real-time communication and monitoring of a large number of stepping product data at the customer site, which can significantly reduce client control costs.

Chapter 2 Performance Indicators

2. 1 Electrical characteristic

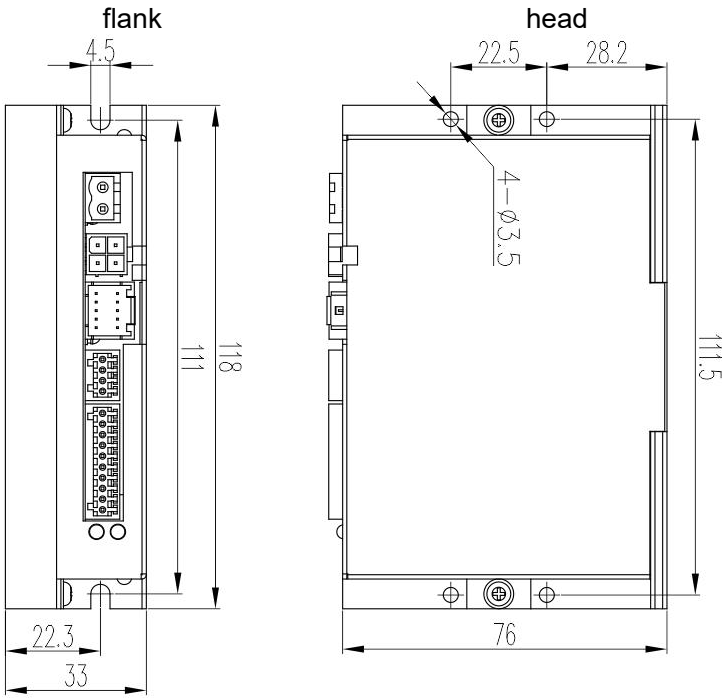
Argument	CL57PR			
	Minimum value	Typical value	Maximum value	Unit
Continuous output current	0	2.0	5.0	A
Input supply voltage	20	-	50	Vdc
Logic input current	1.0	0	7.5	mA
Logic input voltage	5	-	24	V
Insulation resistance	100	-	-	MΩ

2.2 Using environment

Cooling mode	Natural cooling	
Use environment	Use occasion	Try to stay away from other heating equipment, avoid dust, oil mist, corrosive gas, strong vibration places, flammable gas and conductive dust are prohibited
	Temperature	0℃~50℃
	Humidity	40-90%RH (non-condensation)
	Vibration	10~55Hz/0.15mm
Storage temperature	-20℃~+70℃	

Chapter 3 Installation

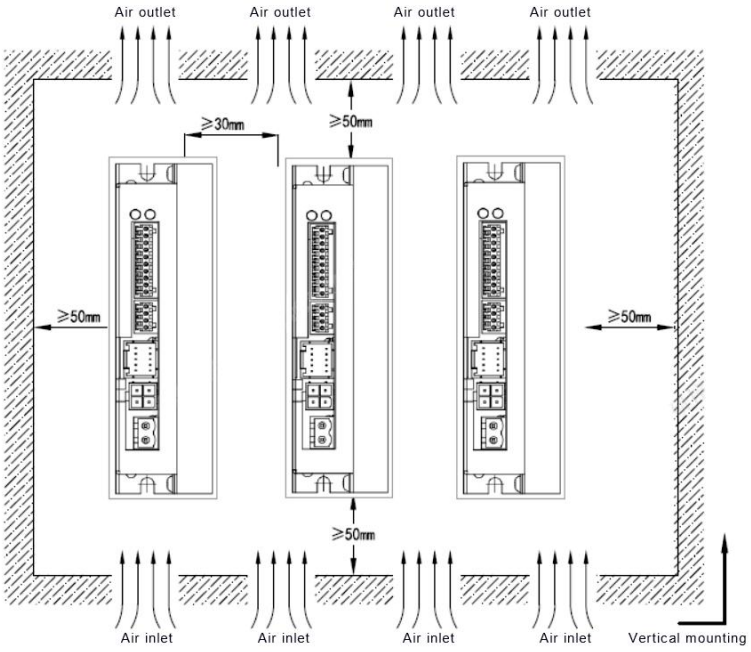
3. 1 Mounting dimension



Mounting dimension drawing (unit: mm)

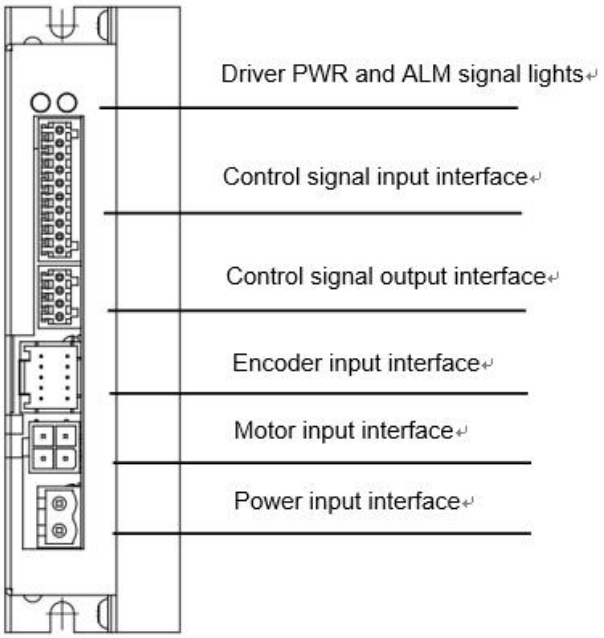
3.2 Installation Methods

When installing the driver, please use the upright side installation to form strong air convection on the driver surface; If necessary, install a fan close to the driver to force the heat to dissipate to ensure that the driver works within the reliable operating temperature range (the reliable operating temperature of the driver is usually within 50°C, and the operating temperature of the motor is within 80°C).

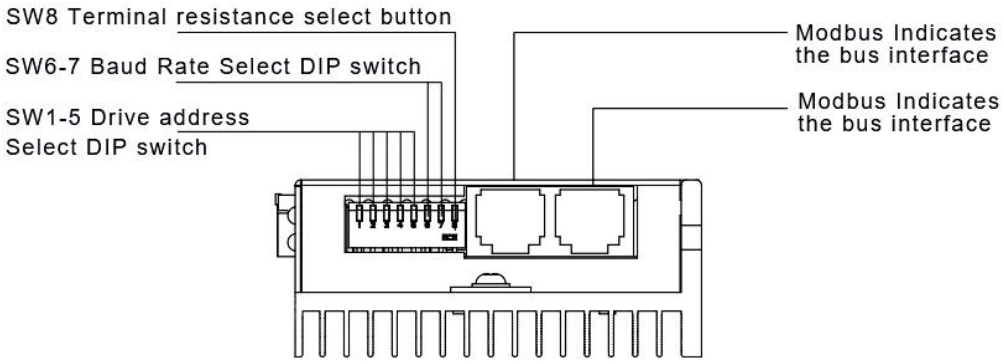


Chapter 4 Driver Ports and Wiring

4.1 Wiring diagram



Driver side wiring diagram



Final drive top diagram

Attention!

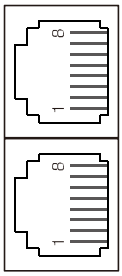
- The personnel involved in wiring must have professional ability.
- No live wiring.
- The wiring can only be carried out after the installation is firm.
- Do not connect the power supply wrong, the input voltage should not exceed 50VDC.

4.2 Port Definition

4. 2. 1 Status light

Identification	Name	Functiom
PWR	Power indicator light	When the power is on, the green indicator lights up.
ALM	Alarm light	Current is overcurrent, the indicator blinks once; In case of overvoltage, the indicator blinks twice; Under voltage, the indicator blinks three times; EEPROM is wrong, the indicator blinks four times; position is out of line, the indicator blinks five times;

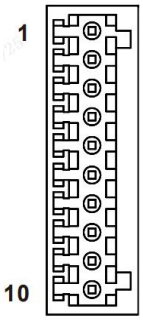
4. 2. 2 MODBUS communication port

Port	Lead	Symbol	Function
	1	RS-485-A	Data communication interface
	2	RS-485-B	
	3	NC	Reserve
	4	NC	Reserve
	5	RS-485-GND	Grounded common terminal
	6	NC	Reserve
	7	NC	Reserve
	8	NC	Reserve

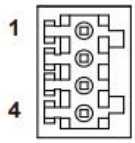
4. 2. 3 Control signal input/output port

The following is the specific definition and functions of the input and output of the CL57PR. The input and output functions can be customized through the register address 2310h-2325h. For example, the input signal can also be configured with stop, emergency stop, probe and other functions. The output can be configured with alarm, in place, brake, output signal and other functions.

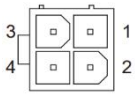
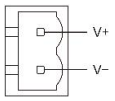
1 Input signal

Port	Lead	Name	Acquiesce	Function
	X0+	X0 Signal input positive end	Point of origin	Two differential input ports, support common Yin and common Yang connection method
	X0-	X0 Signal input negative end		
	X1+	X1 Signal input positive end	Positive limit	
	X1-	X1 Signal input negative end		
	X2	Input terminal X2	Negative limit	Five single-ended input interface, compatible with 5V signal, support common negative and common positive connection. Configurable limit, origin and other signals
	X3	Input terminal X3	Undefined	
	X4	Input terminal X4	Undefined	
	X5	Input terminal X5	Undefined	
	X6	Input terminal X6	Undefined	
	XCOM	Single end input common end	Undefined	

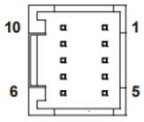
2 Output signal

Port	Lead	Name	Acquiesce	Function
	Y0	Output terminal Y0	-	Three single-ended output outlets, output lock, position back to the original completion signal, support common Yin and common Yang connection method
	Y1	Output terminal Y1	-	
	Y2	Output terminal Y2	-	
	YCOM	Single end output common end	-	

4. 2. 4 Power input/motor output port

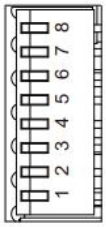
Port	Lead	Name	Default value	Function
	1	A-	Motor interface	Two phase stepper motor connector
	2	A+		
	3	B-		
	4	B+		
	1	V+	Power interface	DC 24-50V
	2	V-		

4. 2. 5 Encoder input port

	Serial number	Symbol	Name	Function
	1	NC	Reserve	Reserve
	2	NC		
	3	EZ+	Encoder Z phase input positive/negative end	Encoder Z channel positive input/negative input
	4	EZ-		
	5	GND	Encoder power grounding	Encoder power grounding
	6	+5V	Encoder power Supply	Encoder 5V power supply
	7	EA-	Encoder phase A input positive/negative end	Encoder A channel positive input/negative input
	8	EA+		
	9	EB-	Encoder B phase input positive/negative end	Encoder B channel positive input/negative input
	10	EB+		

4.3 Dial setting

CL57PR bus stepper motor driver uses 8-bit dial switch to set driver address, communication baud rate and terminal resistance, detailed description is as follows:

Port	Lean	Symbol	Name	Function
	1	SW1	Code dip switch	Drive address setting
	2	SW2		
	3	SW3		
	4	SW4		
	5	SW5		
	6	SW6		Communication baud rate setting
	7	SW7		
	8	SW8		120 OHM terminal resistance effective

4.3.1 Communication baud rate setting

SW6	SW7	Baud rate
ON	ON	9600
OFF	ON	19200
ON	OFF	38400
OFF	OFF	115200

4.3.2 Terminal resistance setting

SW8	**120** OHM terminal resistance effective
OFF	Invalid
ON	Valid

The following is the terminal resistance dialing situation according to the different use scenarios. Please dial the code according to the actual use scenario, otherwise it may cause abnormal communication and other conditions. At the same time, please ground according to the standard wiring requirements to avoid communication interference.

PLC/ Communication master station	Single drive	Cascading multiple drivers (two or more)
Yes and dial the terminal resistance	No dialing	Last call
Terminal resistance is present but not dialed	To dial code	First and last dial
No terminal resistance (and no additional)	To dial code	First and last dial

4.3.3 Terminal resistance setting

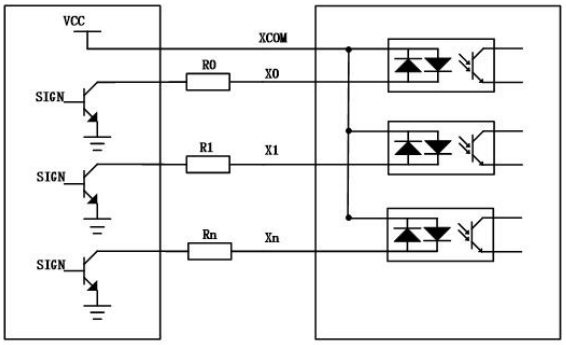
This driver uses RS-485 bus and can control up to 30 drivers at the same time. The communication address of the driver is set by a 5-bit dial switch, and the address setting range is 0-31, where address 0 is reserved for the system. When the address of the driver is set to be greater than 31, it needs to be set and saved by the upper debugging software, and the switch needs to be set to OFF. As shown in the following table:

SW5	SW4	SW3	SW2	SW1	Address
OFF	OFF	OFF	OFF	OFF	Customization
OFF	OFF	OFF	OFF	ON	1
OFF	OFF	OFF	ON	OFF	2
OFF	OFF	OFF	ON	ON	3
OFF	OFF	ON	OFF	OFF	4
OFF	OFF	ON	OFF	ON	5
OFF	OFF	ON	ON	OFF	6
OFF	OFF	ON	ON	ON	7
OFF	ON	OFF	OFF	OFF	8
OFF	ON	OFF	OFF	ON	9
OFF	ON	OFF	ON	OFF	10
OFF	ON	OFF	ON	ON	11
OFF	ON	ON	OFF	OFF	12
OFF	ON	ON	OFF	ON	13
OFF	ON	ON	ON	OFF	14
OFF	ON	ON	ON	ON	15
ON	OFF	OFF	OFF	OFF	16
ON	OFF	OFF	OFF	ON	17
ON	OFF	OFF	ON	OFF	18
ON	OFF	OFF	ON	ON	19
ON	OFF	ON	OFF	OFF	20
ON	OFF	ON	OFF	ON	21
ON	OFF	ON	ON	OFF	22
ON	OFF	ON	ON	ON	23
ON	ON	OFF	OFF	OFF	24
ON	ON	OFF	OFF	ON	25
ON	ON	OFF	ON	OFF	26
ON	ON	OFF	ON	ON	27
ON	ON	ON	OFF	OFF	28
ON	ON	ON	OFF	ON	29
ON	ON	ON	ON	OFF	30
ON	ON	ON	ON	ON	31

4. 4 Input/output port operation

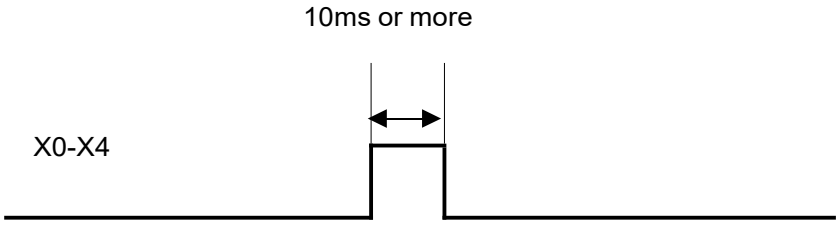
CL57PR driver provides 7 channels of photoelectric isolation input interface, including 2 channels of differential signal input, 5 channels of single-ended signal input, compatible with common negative and common positive connection method; 3 way photoelectric isolation single end output interface, compatible with common negative and common positive connection.

Among them, 2 differential signals are internal high-speed optocoupler isolation, which can be configured for external pulse direction or double pulse control, and can also be configured for ordinary differential input input terminal. The input signal voltage is 5V, and when it is higher than 5V, it needs to be limited by series resistance (such as 2~3K resistance in series when the input signal is 24V). 5 single-ended signal input, when the input signal voltage is higher than 24V, the current can be limited according to the need of external series resistance, as shown in the following figure:



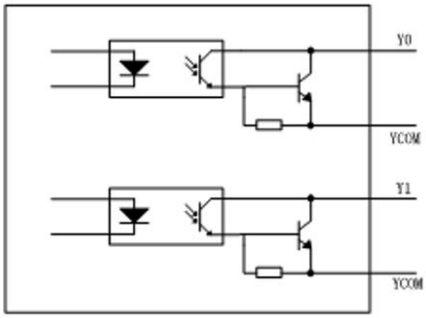
Input terminal connection reference circuit

The level pulse width of the input signal needs to be greater than 10ms, otherwise the driver may not respond properly. The timing diagram of X0-X3 is shown in the figure below.



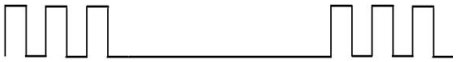
X0-X4 timing diagram

The driver provides two optocoupler isolated output terminals, and the wiring is as follows:



Chapter 5 Driver Status Indicators

The CL57PR driver mainly has the following alarm information. After the driver alarms, the alarm indicator flashes several times according to the alarm code. The alarm code and handling method are as follows.

Fault code	Fault information	ALM indicator blinking	Resetting
Err1:0x01	Overcurrent or interphase short circuit		Power-off reset
Err2:0x02	Overvoltage of supply		Automatic restoration of standard voltage
Err3:0x03	Undervoltage of supply		Automatic restoration of standard voltage
Err4:0x04	EEPROM error		Power-off reset
Err5:0x05	Position overshoot		Power failure, manual reset

Chapter 6 General Troubleshooting methods

phenomenon	Possible situation	Solution measure
Motor failure	The power light is off	Check the power supply circuit. The power supply is normal
	The motor locks the shaft but does not turn	The IO signal is weak and the signal current is increased
	Too little speed	Selection speed
	Whether the release signal MF is connected	Will release the signal MF does not connect
	Instruction input error	Check whether the upper computer has a switch output
Motor steering error	Motor reversal	Replace motor wiring sequence or adjust instruction direction
	The motor line has a break	Check whether the cable is in poor contact
	The motor has only one direction	Input port damage
Alarm indicator light	The motor wire is connected incorrectly	Check the wiring
	The voltage is too high or low	Check power supply
	The motor or drive is damaged	Replace the motor or drive
Wrong position or speed	Signal interference	Eliminate interference, reliable grounding
	Instruction input error	Check the upper computer instructions to ensure correct output
	Speed setting error	Check the DIP switch status and connect it correctly
	Motor tripping	Check whether the command speed is too large and the motor selection is small
The driver terminal is burned out	Short-circuit between terminals	Check the power polarity or external short circuit
	The internal resistance between terminals is too large	Check whether excess solder is added to the wire and wire connection to form tin pellets
Motor stalling	The acceleration and deceleration time is too short	Reduce the command acceleration or increase the driver filter parameter
	Motor torque too small	Select high torque motor
	Heavy load	Check the load weight and quality, adjust the mechanical structure
	Too little current	Check dip switches to increase the output current of the driver